Date: 11/18/2013

Project Name: Transradial Prosthetic Arm

Group Number: 15

Group Members: Kendall Gretsch, Henry Lather, Kranti Peddada

**Current status of project:**We are continuing to work on the prototype. We have printed and attached together all of the fingers and palm block for the hand. For the electronics portion, we are now able to turn the servomotor a specific number of degrees based on the acceleration. We are now trying to write software to translate the acceleration data into position data. This past weekend work on the paper has also started.

**Work planned for next week:** We plan to continue working on the prototype and paper. We will start designing the socket and continue making progress on the software. We also hope to put together the different elements of our design, and start having the electrical components interface with the hand. Finally, we will complete the Design Safe for our project.

**Anything needed from client or TA or instructor to continue work:** Nothing is needed right now.